

**CAS 701 Fall 2002**

# **02 Mathematical Models**

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# Kinds of Mathematical Models

- There are many kinds of mathematical models
- The major categories are:
  1. Mathematical models constructed from basic mathematical objects (such as sets, functions, and relations)
  2. Mathematical structures (collections of objects related in certain ways)
  3. Axiomatic theories (which axiomatically specify a set of mathematical structures)
  4. Abstract machines for performing computations

# Sets

- A **set** is a collection of objects with a **membership** relation (usually represented by  $\in$ )
- Almost any mathematical concept can be expressed in terms of set and membership
- There are various paradoxes that involve sets that are “too big”
  - Example: **Russell’s Paradox** involving the set of all sets that do not contain themselves
- **Zermelo-Fraenkel (ZF) set theory** is a first-order formalization of set theory that is intended to avoid the set-theoretic paradoxes
  - It is widely used as a lingua franca for mathematics

# Set Concepts

- Basic properties: membership, subset, cardinality
- Basic operations:
  - union, intersection, complement, difference, symmetric-difference
  - cartesian product (product), disjoint union (sum)
  - power set
- Special sets: the emptyset, universal sets, tuples, functions, relations, ordinals, cardinals

# Functions

- There are two definitions of a function:
  1. A **function** is a rule  $f : I \rightarrow O$  that associates members of  $I$  (inputs) with members of  $O$  (outputs)
    - Every input is associated with at most one output
    - Some inputs may not be associated with an outputExample:  $f : \mathbf{Z} \rightarrow \mathbf{Q}$  where  $x \mapsto 1/x$
  2. A **function** is a set  $F \subset I \times O$  such that if  $(x, y), (x, y') \in F$ , then  $y = y'$
- Each function  $f$  has a **domain**  $D \subseteq I$  and a **range**  $R \subseteq O$
- A set can be represented as a special kind of function (e.g., as a **unary predicate**, a **characteristic function**, or an **indicator**)

# Function Concepts

- Basic properties:
  - partial, total
  - arity (0, 1,  $n \geq 2$ , multiary)
  - injective, surjective, bijective
  - image, reverse image
- Basic operations: composition, restriction, inverse
- Special functions: the empty function, identity functions, choice functions

# Relations

- An  $n$ -ary **relation** is a set  $R \subseteq A_1 \times \cdots \times A_n$  ( $n \geq 1$ )
  - Any set can be considered as a unary relation
  - Any nonunary relation can be considered as a binary relation
- Functions are considered as special relations
  - An  $n$ -ary function  $f : A_1 \times \cdots \times A_n \rightarrow B$  is identified with the corresponding  $(n + 1)$ -ary relation
$$R_f \subseteq A_1 \times \cdots \times A_n \times B$$
- An  $n$ -ary relation can be represented by an  $n$ -ary predicate

# Relation Concepts

- Basic relation properties:
  - reflexive, symmetric, transitive
- Basic relation operations:
  - domain, range
  - composition, inverse
- Special relations: the empty relation, universal relations, equivalence relations

# Example: Program Specifications

Various kinds of functions and relations can be used to specify computer programs:

- **Input/output specification**

- A function  $f : I \rightarrow O$  that maps inputs to outputs
- A relation  $R \subseteq I \times O$  that relates inputs and outputs

- **Before/after specification**

- A function  $f : I \times S \rightarrow O \times S$  that maps inputs and before-states to outputs and after-states
- A relation  $R \subseteq I \times S \times O \times S$  that relates inputs, before-states, outputs, and after-states

- **Trace specification**

- A function  $f : I \times S^* \rightarrow O \times S^*$  that maps inputs and before-traces to outputs and after-traces
- A relation  $R \subseteq I \times S^* \times O \times S^*$  relates inputs, before-traces, outputs, and after-traces

# Mathematical Structures

- A **mathematical structure** consists of:
  1. A set of elements called the **domain**
  2. A set of distinguished elements, functions, and relations called the **signature** that impose a structure on the set of elements
- The signature usually determines a **language** for describing and making assertions about the elements of the domain

# Examples of Mathematical Structures

- Orders (e.g., pre, partial, linear, well)
- Graphs
- Lattices and boolean algebras
- Algebraic structures (e.g, monoids, groups, rings, fields, modules, vector spaces)
- Number systems (e.g, integer, rational, real, complex, hyperreal, ordinal, cardinal, surreal)
- Data structures used in Computer Science (e.g, arrays, stacks, queues)

# Axiomatic Theories

- **Axiomatic theory** = formal language + set of axioms
- **Language**: vocabulary for describing and making assertions about objects and their properties
- **Axioms**: assumptions about the objects and properties
  - Specify a set of mathematical structures (called the **models** of the theory)
  - Basis for proving theorems
- Benefits:
  - **Conceptual clarity**: inessential details are omitted
  - **Generality**: theorems hold in all models

# Abstract Machines

- An **abstract machine** or **automaton** is an abstract device for performing computations
- A **universal machine** is a machine that can compute any computable function; examples:
  - Turing machine
  - Unlimited register machine
- A **state machine** is a machine that computes in a stepwise fashion in which each step includes receiving input, producing output, and changing state; examples:
  - Finite automaton
  - Pushdown automaton
  - Finite state machine

# Turing Machines (Alan Turing, 1936)

A **(deterministic) Turing machine**  $M$  consists of the following components:

1. A two-way infinite **tape** composed of cells
2. A **tape head** that can read a cell and then (a) write a symbol in it, (b) move left, or (c) move right
3. A **finite state control mechanism**
4. Fixed finite set  $\{s_1, \dots, s_m\}$  of **tape symbols**
5. Fixed finite set  $\{q_1, \dots, q_n\}$  of **states**
6. A **transition relation** consisting of a finite set  $T$  of quadruples of the form  $(q_i, s_j, s_k, q_l)$ ,  $(q_i, s_j, L, q_l)$ , or  $(q_i, s_j, R, q_l)$  such that (a)  $1 \leq i, l \leq n$ , (b)  $0 \leq j, k \leq m$ , and (c) for all  $(q_i, s_j)$ , there is at most one  $(q_i, s_j, \alpha, \beta) \in T$

# Finite State Machines

A **finite state machine**  $M$  consists of the following components:

1. A fixed finite set  $S$  of **states** including an **initial state**
2. A fixed (possibly infinite) set  $I$  of **inputs**
3. A fixed (possibly infinite) set  $O$  of **outputs**
4. A **next state** relation  $ns \subseteq S \times I \times S$
5. An **output** relation  $out \subseteq S \times I \times O$

$M$  is **deterministic** if the relations are functions, i.e.,  
 $ns : S \times I \rightarrow S$  and  $out : S \times I \rightarrow O$